C. elegans learning and decision making in T-shaped mazes **MECHANICAL** Eleni Gourgou ^{1,2}, Kavya Adiga ³, Chieh Cheh ⁴, Ao-Lin Allen Hsu ^{2,5} **University of Michigan** ENGINEERING **Medical School** UNIVERSITY OF MICHIGAN

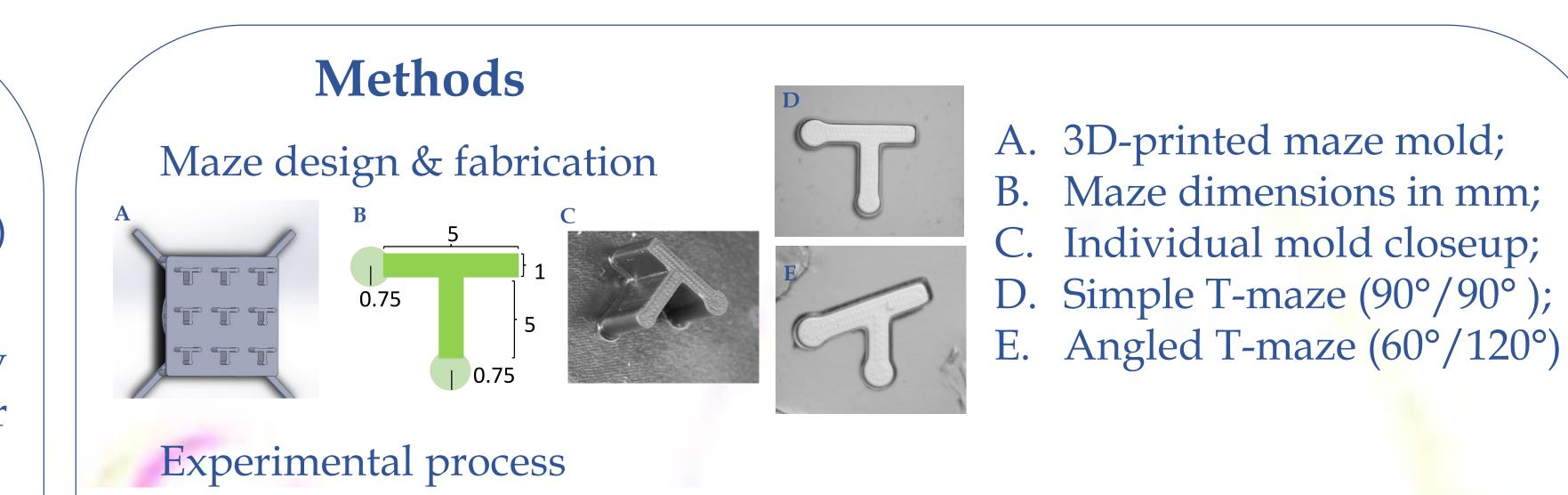
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Basic Control experimen

Background & Introduction

C. elegans demonstrate non-associative learning (habituation) and they are capable of associative learning and imprinting.

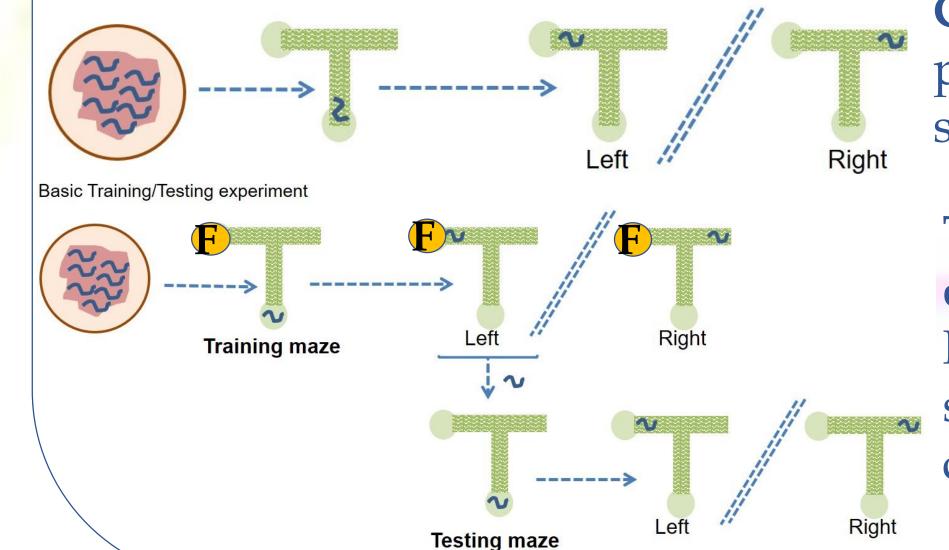
Mazes have been broadly used as a tool to investigate the ability of organisms to learn navigation-related tasks and to test their decision making process.



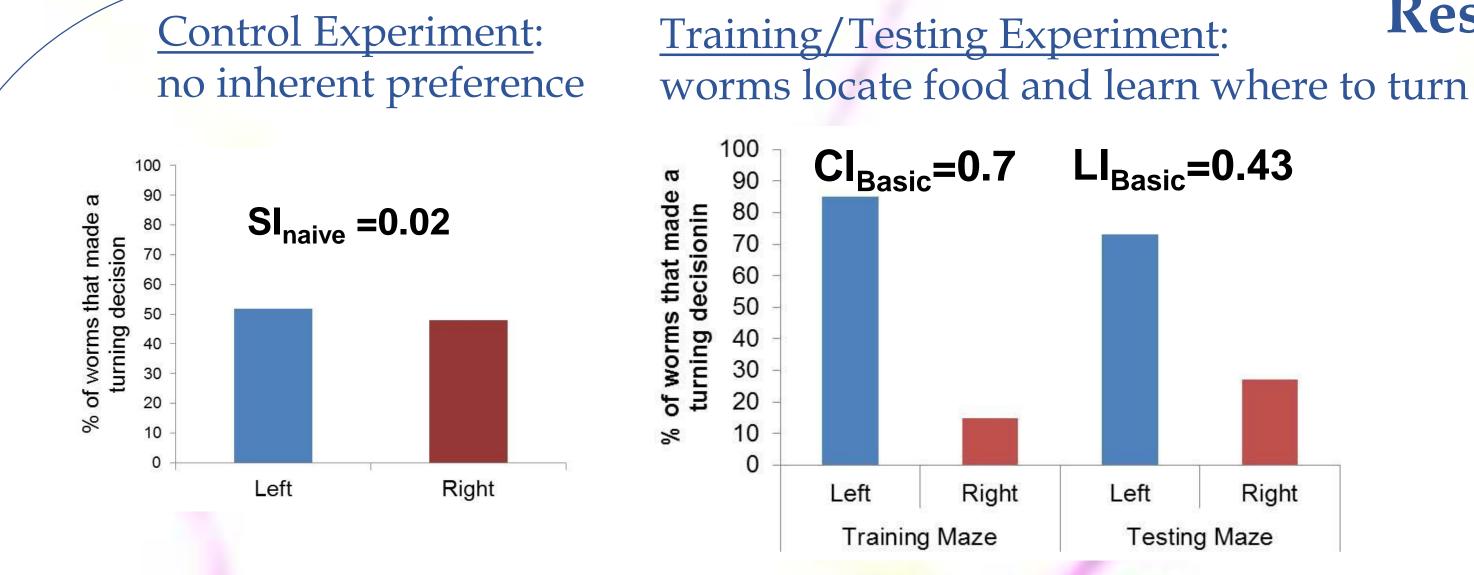
Control experiment (empty maze): process followed for N2 and mutant strains, as a reference case.

We introduce a **custom-made T-shaped maze platform**, the Worm-Maze, to explore C. elegans' navigation, learning and decision making. We characterize this new behavior in relation to diverse environmental cues, and we explore the role of chemosensation, mechanosensation and propriosensation.

We show that aging has a differential effect on maze-related behaviors, as middle-aged worms can still locate food in the maze, but their learning ability is severely declined.



Training (food)/Testing (no food) **experiment:** process followed for N2 and mutant strains with Tshaped mazes, and for N2 with cantered mazes.



Results

Solving Index, SI= (n_L-n_R)/Total worms-n_{censored}

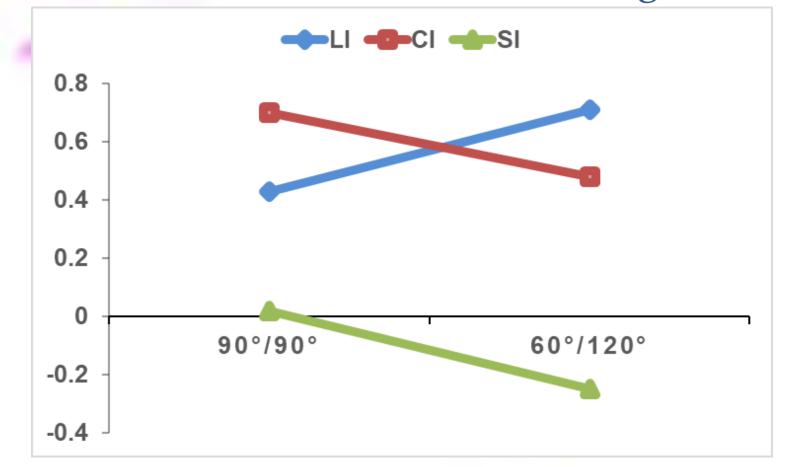
<u>Chemotaxis Index</u>, CI= SI_{Train}-SI_{Naive} (comparing performance in Training maze) <u>Learning Index</u>, LI= SI_{Test}-SI_{Naive} (comparing performance in Testing maze)

 n_{L} : worms that turned Left / towards food, n_{R} : worms that turned Right / not towards food n_{censored}: worms censored (immobile, inconclusive, lost – given as % in Tables below) $SI_{Naive} = (n_L - n_R) / Total worms - n_{censored}$ (naïve worms, maze **empty-Control**) $SI_{Train} = (n_L - n_R) / Total worms - n_{censored}$ (worms in **Training maze**), $SI_{Test} = (n_L - n_R) / Total worms - n_{censored}$ (worms in **Testing maze**)

0.8



Learning is sufficient to overcome inherent aversion for acute angles



<i>p</i> -values	Control (empty) 60°/120°	Training/Testing,60°/120°	<i>p</i> -values	Smooth ma
SI _{60/120} to SI _{90/90}	0.04, n=75, 8%		SI _{Smooth} to SI _{Basic}	0.77, n=45, 10
$\text{CI}_{60/120}$ to $\text{SI}_{90/90}$		<0.001, n=88, 9%	CI _{Smooth} to SI _{Basic}	<0.001 , n=103
CI _{60/120} to CI _{90/90}		<0.001, n=88, 9%	CI_{Smooth} to SI_{Smooth}	0.001, n=103,
CI _{60/120} to SI _{60/120}		<0.001, n=88, 9%	CI _{Smooth} to CI _{Basic}	<0.001 , n=103
LI _{60/120} to SI _{90/90}		0.003, n =45, 13%	LI _{Smooth} to SI _{Basic}	0.64, n=40, 18
LI _{60/120} to LI _{90/90}		0.57, n=45, 13%	LI _{Smooth} to SI _{Smooth}	0.65, n=40, 18
LI _{60/120} to SI _{60/120}		<0.001, n=45, 13%	LI _{Smooth} to LI _{Basic}	0.01 , n=40, 18

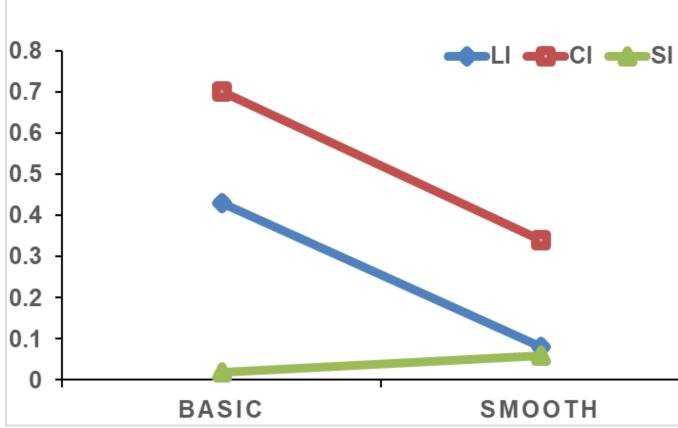
Statistical Analysis

Comparisons were made by the binomial probability distribution test in MATLAB R2016b (Mathworks, USA), using the binocdf and binopdf functions of Statistics and Machine Learning Toolbox. Differences are statistically significant when *p*-value<0.05.

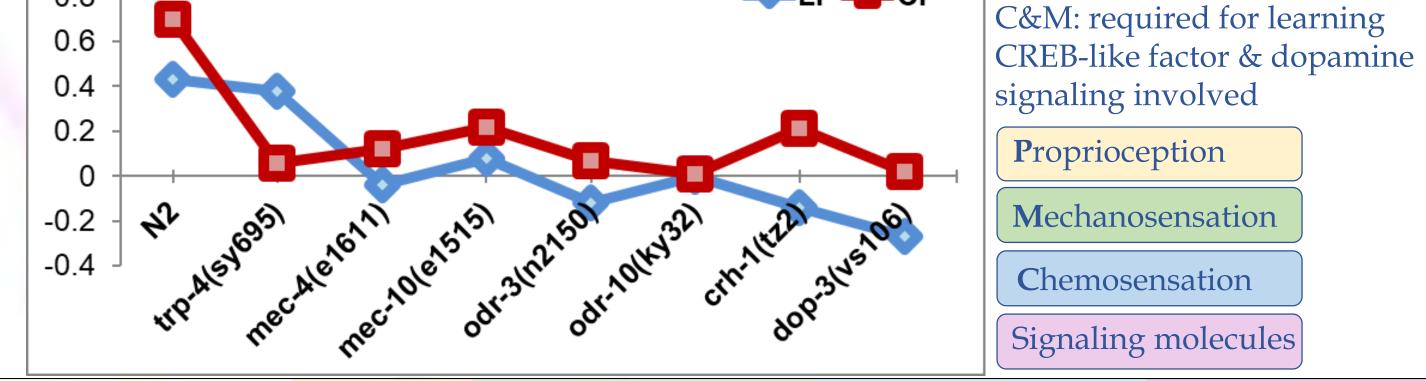
<u>Absence of tactile input compromises</u> navigation and learning ability

Testing Maze

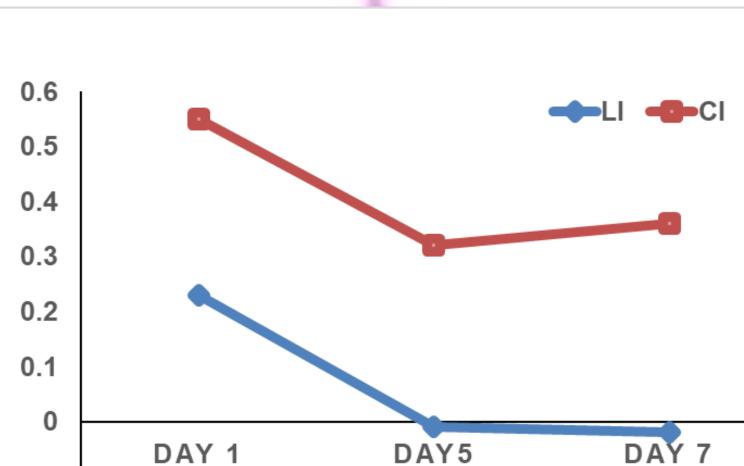
Right



<i>p</i> -values	Smooth maze
SI _{Smooth} to SI _{Basic}	0.77, n=45, 10%
CI _{Smooth} to SI _{Basic}	<0.001 , n=103, 16%
CI_{Smooth} to SI_{Smooth}	0.001, n=103, 16%
CI _{Smooth} to CI _{Basic}	<0.001, n=103, 16%
LI _{Smooth} to SI _{Basic}	0.64, n=40, 18%
LI _{Smooth} to SI _{Smooth}	0.65, n=40, 18%
LI _{Smooth} to LI _{Basic}	0.01, n=40, 18%



<i>p</i> -values	N2	<i>trp-4</i>	<i>mec-4</i>	<i>mec-10</i>	<i>odr-</i> 3	odr-10	<i>crh-1</i>	<i>dop-3</i>
	(wild type)	(sy695)	(e1611)	(e1515)	(n2150)	(ky32)	(tz2)	(vs106)
CI _{Strain} to	<0.001	0.48	0.21	0.047	0.44	0.83	0.02	0.73
SI _{Naive}	n=116,12%	n=111, 5%	n=96, 6%	n=88, 8%	n=95, 10%	n=85, 7%	n=105,13%	n=109, 9%
CI _{Strain} to		<0.001	<0.001	<0.001	<0.001	<0.001	<0.001	<0.001
CI _{N2}		n=111, 5%	n=96, 6%	n=88, 8%	n=95, 10%	n=85, 7%	n=105,13%	n=109, 9%
LI _{Strain} to	<0.001	0.02	1	0.63	0.64	1	0.44	0.16
SI _{Naive}	n=70, 5%	n=40, 9%	n=37, 13%	n=40, 11%	n=40, 16%	n=39, 9%	n=40, 16%	n=40, 7%
LI _{Strain} to LI _{N2}		0.39 n=40, 9%	0.001 n=37, 13%	0.014 n=40, 11%	<0.001 n=40, 16%	0.003 n=39, 9%	<0.001 n=40, 16%	<0.001 n=40, 7%



<u>The differential effect of aging</u> : Learning ability declines first				
<i>p</i> -values	Day 1	Day 5	Day 7	
CI _{Dayx} to SI _{Naive_Day1}	<0.001 n=120, 5%	0.0061 n=76, 5%	0.002 n=64, 3%	
CI_{Dayx} to CI_{Day1}		0.01 n=76, 5%	0.03 n=64, 3%	
LI _{Dayx} to SI _{Naive_Day1}	<0.001 n=62, 13%	1 n=41, 10%	1.12 n=40, 2%	
LI _{Dayx} to LI _{Day1}		0.03	0.02	

DAY	1	DAY5

Conclusions

- First-time evidence of space-related **navigational learning in** *C. elegans*
- Example Learning observed after a single training session and is detected very shortly after

Learning is a multisensory behavior and leads to biased decision making

- Worm-Maze is suitable for running behavioral assays to monitor decision making, learning and sensory integration in worms
- Aging has a differential effect on worms' behaviors, implying that aging does not affect all neurons and neuronal circuits uniformly

Acknowledgments

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